

# A Class of Precomputation-based Distance-bounding Protocols

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**Abstract**—Distance-bounding protocols serve to thwart various types of proximity-based attacks, such as relay attacks. A particular class of distance-bounding protocols measures round trip times of a series of one-bit challenge-response cycles, during which the proving party must have minimal computational overhead. This can be achieved by precomputing the responses to the various possible challenges. In this paper we study this class of precomputation-based distance-bounding protocols. By designing an abstract model for these protocols, we can study their generic properties, such as security lower bounds in relation to space complexity. Further, we develop a novel family of protocols in this class that resists well to mafia fraud attacks.

## 1. Introduction

Physical proximity is a common requirement in many access control policies, particularly in those involving physical access. Most real-world security systems would rise a security alert if a door has been opened remotely. An electronic toll payment made by a user whose car is parked in front of his home can also hardly be considered an expected behavior. Some access control mechanisms have been designed in such a way that physical proximity is enforced easily, e.g., mechanical locks or biometric identification. However, due to the open nature of wireless channels, providing the same kind of guarantee in wireless systems is far from trivial.

Simple proximity enforcing techniques, such as setting up small communication timeouts or short-range communication channels, can be easily circumvented in practice by a variety of attacks [1]. Perhaps, the most popular and devastating of such attacks is *mafia fraud* [2], also known as *relay attack* [3]. This fraud simply consists in relaying all communication between two wireless devices, making them believe that they have a direct communication.

Case in point, let's assume that Mallory wants to get unauthorized access to Alice's office, and that Alice opens the door of her office by simply swiping her personal contactless token over the door's card reader. Mallory can achieve her goal by executing a mafia fraud attack as follows. First, a friend of Mallory approaches Alice while she

is away from the office. At the same time, Mallory, who is in front of the door of Alice's office, uses a wireless device that pretends to be Alice's contactless token. All messages from the door are relayed by Mallory's wireless device to Mallory's friend, who also uses a wireless device to send these messages to the contactless token of Alice. Similarly, all messages from Alice's contactless token are relayed back to the door. Even though Alice nor her token is near the door, her relayed credentials will eventually be accepted by the door and Mallory will get access to Alice's office.

The most reliable countermeasure against proximity-based attacks, such as mafia and distance fraud [4], is *distance-bounding*. This countermeasure typically consists in measuring the Round Trip Time (RTT) of a message exchange, i.e., the time a message takes to travel from a verifier to a prover and back [5]. If we denote the propagation speed of the communication channel by  $c$ , the round trip time by  $\Delta_t$  and the processing time taken by the prover to send back the message by  $t_d$ , then the distance between the verifier and the prover is computed by the equation  $d = c \times (\Delta_t - t_d)$ .

The first design of a distance-bounding protocol based on RTT measurements dates back to 1993 [4]. Since then, more than 30 distance-bounding protocols have been proposed<sup>1</sup>, each of them bringing improvements over their predecessors or adding new features. Amongst them, we can find a large class of protocols (e.g., [6], [7], [8], [9], [10], [11]) following two core principles raised by Hancke and Kuhn in 2005 [3].

- RTT measurements should exchange single-bit messages. This reduces the processing time by allowing the prover to instantly reply upon reception of a single bit message.
- Each RTT measurement ought to be based on a challenge-response authentication scheme so that, even if the protocol stops after a few RTT measurements, some guarantees of proximity can be provided.

Distance-bounding protocols adhering to the principles of the Hancke and Kuhn (HK) protocol [3] normally consist of two phases. The first phase is the *slow phase*, where the

1. <http://www.avoine.net/rfid/index.php>

verifier and the prover exchange nonces and use a shared key to secretly *precompute* a lookup table with potential responses for the next phase. The second phase, known as *fast phase*, consists of  $n$  RTT measurements. At the  $i$ th RTT measurement with  $i \in \{1, \dots, n\}$ , the verifier sends a random bit-challenge  $c_i$  to the prover and starts a clock. The prover replies instantly to the challenge  $c_i$  by using the precomputed lookup table. Upon reception of the prover's reply, the verifier stops the clock and computes the RTT ( $\Delta_i$ ). The protocol finishes correctly if all responses are correct, and if  $\Delta_i \leq \Delta$  for every  $i \in \{1, \dots, n\}$  given some time threshold  $\Delta$ .

The simplicity of distance-bounding protocols based on the above scheme makes it attractive for ubiquitous wireless technologies such as RFID systems. However, to the best of our knowledge, all these protocols fall short in terms of resistance to mafia fraud attacks in comparison to cryptographically more expensive approaches, such as the Brands and Chaum protocol [4]. More precisely, given a fixed number of RTT measurements  $n$ , the best-known mafia fraud attack to the Brands and Chaum protocol has probability of success  $\frac{1}{2^n}$  [4], while no protocol following the above principles reduces the success probability of the same attack below  $\frac{1}{2^n}(1 + \frac{n}{2})$  [7]. This good performance of the Tree-based protocol in [7] comes at the price of an exponential space requirement. It is not known if the same performance can be achieved at lower memory costs. Further, it is also an open question whether this lower bound can be reduced under the two core principles mentioned above.

Because all protocols based on these principles have a similar shape, it would be natural and useful to consider them as instantiations of the same protocol scheme, with slight variations. That would provide us with a mathematical model, allowing us to study theoretical properties that hold for a large class of protocols. In this article, we propose such a model based on deterministic finite automata (DFAs). In more detail, our contributions are the following.

- We propose an abstract model for distance-bounding protocols that use precomputation and look-up operations. The proposed model is based on DFAs and captures several state-of-the-art distance-bounding protocols, such as [3], [6], [7], [10], [11], [12].
- Considering  $n$  to be the number of RTT measurements performed during a single execution of the protocol, we prove that  $\frac{1}{2^n}(1 + \frac{n}{2})$  is a tight lower bound on the security of this type of protocols against mafia fraud. This result indicates that, within our model, the Tree-based protocol [7] is optimal in terms of mafia fraud resistance.
- We study theoretical properties of a subclass of protocols within the proposed model, such as its resistance to pre-ask attacks and its space complexity.
- We define a novel family of protocols within our model that has good security properties in terms of resistance to mafia fraud in relation to its memory.

The rest of this article is organized as follows. In Sec-

tion 2 we provide some basic knowledge on distance bounding protocols and discuss related literature. The HK protocol and the Tree-based protocol explained in this section will be used throughout this paper as examples. In Section 3, we define an abstract model for the description of a class of distance-bounding protocols. Space complexity and other relevant properties of this class are introduced in Section 4. Later on, in Section 5, we perform a generic security analysis. Finally, in Section 6, we describe a protocol, or rather a family of protocols, of which the resistance to mafia fraud is arbitrary close to optimal.

## 2. Related work

### 2.1. Distance-bounding protocols

Distance-bounding protocols are authentication protocols that, in addition, compute an upper bound on the distance between the two parties involved in the protocol. The distance estimation process relies on a concrete physical law, stating that Radio Frequency (RF) signals travel at the speed of light. By using a communication channel whose propagation speed is close to the physical limit, a distance-bounding protocol ensures that an adversary interfering in an RTT measurement by relaying messages cannot decrease the estimated distance. In the same vein, most distance-bounding protocols aim to minimize the processing time on the prover side. A small and deterministic processing time will improve the precision of the distance estimation and prevents attacks where the adversary overlocks the prover [4], [13], [14].

A large variety of distance-bounding protocols exist. Some are based on expensive cryptographic operations such as signatures and commitment schemes [4], [15], [16]. Others use error detection and correction techniques to deal with potential noise during the RTT measurements [17]. We can even find approaches addressing location-privacy concerns [18]. Nevertheless, there are common features shared by most distance-bounding protocols. For example, they typically exchange 1-bit messages for RTT measurements, which reduces the processing time by allowing the prover to instantly reply upon reception of a single bit message. Exceptions to this rule are, for example, the Munilla and Peinado protocol [19] and its generalization [20].

Another characteristic that clearly splits the set of distance-bounding protocols into two classes is the presence or not of a so-called *final slow phase*. We recall that a fast phase consists of consecutive message exchanges intended for RTT measurement, while a slow phase is formed by any other type of message. Hence, a slow phase is said to be final if it represents the end of the protocol execution. It was in 2005, twelve years after the pioneering Brands and Chaum protocol [4], when Hancke and Kuhn proposed the first distance-bounding protocol without final slow phase [3]. Given its relevance and impact on many recent protocols, we next detail this protocol in extenso (see also Figure 1).

The Hancke and Kuhn protocol (HK) consists of a slow phase followed by a fast phase. In the slow phase, the verifier

and the prover exchange nonces  $N_V$  and  $N_P$  and use a keyed pseudo-random function (PRF) to agree on a bit-sequence  $B = b_1 \dots b_{2n}$ . This bit sequence has size  $2n$ , where  $n$  is a parameter representing the number of RTT measurements. The fast phase consists of  $n$  consecutive rounds. At the  $i$ th round with  $i \in \{1, \dots, n\}$ , the verifier sends a random bit-challenge  $c_i$  to the prover and starts a clock. Upon reception of  $c_i$ , the prover replies with the bit  $b_{2i+c_i-1}$ . Immediately after receiving the prover's answer, the verifier stops the clock and computes the RTT,  $\Delta_i = t_f - t_s$ . The HK protocol finishes correctly if all responses are correct according to the challenges and bit-sequence  $B$ , and if  $\Delta_i \leq \Delta$  for every  $i \in \{1, \dots, n\}$  given some time threshold  $\Delta$ .

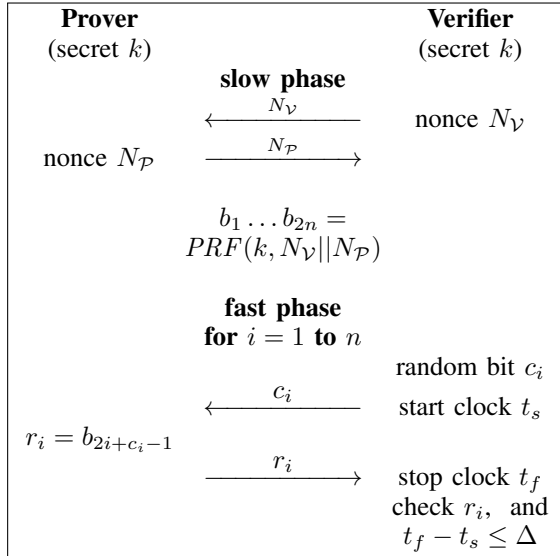


Figure 1. Hancke and Kuhn's protocol

Because Hancke and Kuhn's protocol relies on a single pseudo-random function, it is considered to be the first distance-bounding protocol suitable for resource-constrained technologies such as RFID systems. An additional feature of this protocol is that, during the fast phase, the prover computes the correct reply to the verifier's challenge via a simple lookup operation. This significantly reduces the processing time, ergo it sticks to the basic principles of RTT measurements. The drawback, however, of the HK protocol is its low resistance to mafia fraud. An adversary could execute a so-called *pre-ask* [21] attack as follows. First, the adversary relays all the communication between the prover and the verifier during the slow phase. Before the beginning of the fast phase, the adversary claims to be the legitimate verifier and queries the prover  $n$  times with the same challenge 0. As a result, the adversary receives from the prover the values  $b_1, b_3, \dots, b_{2n-1}$ . Finally, the adversary uses this knowledge to reply to the verifier's challenges during the fast phase. The probability of success of an adversary executing such an attack is  $(3/4)^n$ . This can be easily seen as follows. At every round of the fast phase, the adversary is challenged with a random bit. If this bit is a 0, she will answer with the correct (pre-asked) reply.

Otherwise, if the challenge is 1, she can reply with a random bit, which gives her a chance of  $\frac{1}{2}$  to reply correctly. In total, this gives her a success probability of  $\frac{1}{2} \times 1 + \frac{1}{2} \times \frac{1}{2} = \frac{3}{4}$  per round, leading to  $(3/4)^n$  for  $n$  rounds. For an ideal protocol, the adversary would not be able to achieve any advantage over randomly guessing the reply, leading to a success probability of  $(1/2)^n$ . This probability is achieved by the Brands and Chaum protocol [4], which uses a final slow phase for authentication of the exchanged bits.

In [3], Hancke and Kuhn explain the advantage of avoiding a final slow phase, even at the cost of an apparent decrease in the resistance to mafia fraud, as follows. In terms of execution time and computational complexity, the cost of executing a couple of additional rounds during the fast phase is significantly lower than the cost of performing expensive cryptographic operations and message exchanges over a traditional communication channel. Hence, for practical values of  $n$ , there exists  $m > n$  such that the HK protocol with  $m$  rounds is more efficient than the Brands and Chaum protocol with  $n$  rounds, i.e.,  $(\frac{3}{4})^m < (\frac{1}{2})^n$ .

The precomputation approach started by Hancke and Kuhn has been extended and improved by many recent distance-bounding protocols [6], [7], [8], [9], [10], [11], which we refer to as *HK-like* protocols. Even though they all have their own peculiarities, most of them perform simple lookup operations during the fast phase in order to reply to the verifier's challenges. Exceptions to this rule are the protocols introduced in [8], which uses XOR operations, and [9], which requires the prover to generate random bits during the fast phase.

To the best of our knowledge, the best HK-like protocol in terms of resistance to mafia fraud is the Tree-based protocol proposed by Avoine and Tchamkerten [7] in 2009. Their protocol considers an edge-labeled full-binary tree of depth  $n$  with labels taken from the set  $\{0, 1\}$ , and satisfying that every two edges with a common parent node have different labels. Thus, any bit-sequence  $c_1 c_2 \dots c_i$  with  $1 \leq i \leq n$ , defines a unique path in the tree. At each session, the prover and the verifier securely agree on a vertex-labeling function over the considered tree by using two nonces and a secret key as input to a pseudo-random function. As in the Hancke and Kuhn protocol, the fast phase consists of  $n$  challenges  $c_1, \dots, c_n$ . The prover replies to these challenges with the node's label of the unique path defined by  $c_1 \dots c_n$ . A sketch of this protocol is shown in Figure 2.

In the Tree-based protocol, the probability of success of an adversary executing a pre-ask attack is  $\frac{1}{2^n}(1 + \frac{n}{2})$  [7], which has not been improved yet by any HK-like protocol. The problem is, however, that precomputing a full-binary tree of depth  $n$  is exponential in terms of  $n$ . Avoine and Tchamkerten propose to split the tree into several trees to overcome this problem [7], while in [6] the Tree-based approach is generalized to graphs of arbitrary size. From a decision-making point of view and according to the framework proposed in [22], graph-based protocols provide relevant features not provided by other types of distance-bounding protocols.

The formal model proposed in this article actually cap-

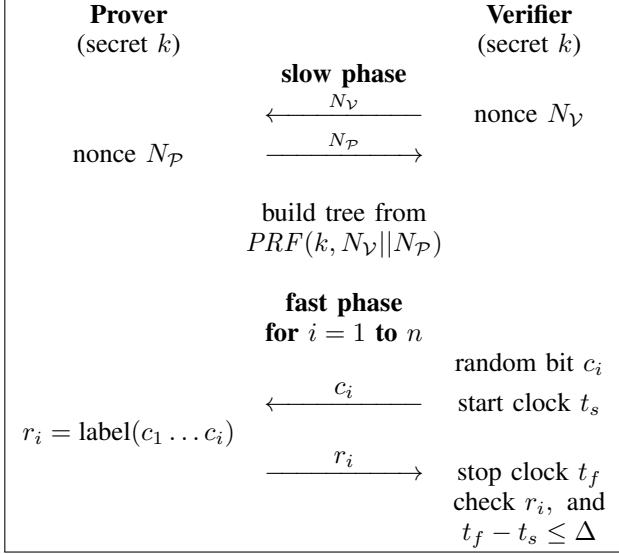


Figure 2. The Tree-based protocol

tures the notion of graph-based distance-bounding protocols, as introduced in [6], [23]. By studying the proposed model we solve the open question of whether there exists a graph-based protocol with security  $\frac{1}{2^n}(1 + \frac{n}{2})$  against a pre-ask attack and whose graph contains a polynomial number of vertices in terms of  $n$ . It is worth remarking that our model is not a simple abstraction and formalization of the notion of graph-based distance-bounding. As we show later, there exists a novel class of distance-bounding protocols within our model with resistance to mafia fraud asymptotically close to  $\frac{1}{2^n}(1 + \frac{n}{2})$ .

## 2.2. Modeling distance-bounding protocols

We notice that the current article is not the first attempt to investigate the limits of distance-bounding protocols without final slow phase. In 2010, Kara et al. [24] defined a class of distance-bounding protocols named *current challenge-dependent protocol*. Similar to the class of protocols that we consider in this article, *current challenge-dependent protocols* don't have a final slow phase. However, there are two main aspects that make Kara et al.'s model significantly different from ours. First, they consider stateless protocols only, in the sense that all RTT measurements are independent of previous ones. Therefore, their model cannot capture, for example, the class of graph-based distance-bounding protocols, which is captured by our model. Second, Kara et al.'s model allows protocols to perform arbitrary computation during the fast phase, as long as this computation depends exclusively on the current challenge and the *session secrets* [24]. Differently, we make the requirement explicit that only lookup operations are allowed, implying that there exist protocols within Kara et al.'s model that are not captured by ours.

## 3. A model based on State-labeled Deterministic Finite Automata

In this section, we provide a simple model that captures a prominent class of distance-bounding protocols based on precomputation and without final slow phase. We model distance-bounding protocols via a particular class of Deterministic Finite Automata (DFA) with labels attached to states. We denote them by *state-labeled DFA*. Formally, a state-labeled DFA is defined as follows.

**Definition 1** (State-labeled DFA). *A state-labeled DFA is a tuple of the form  $(\Sigma, \Gamma, Q, q_0, \delta, \ell)$  where:*

- $\Sigma$  is a finite set of input symbols,
- $\Gamma$  is a finite set of output symbols
- $Q$  is a finite set of states,
- $q_0 \in Q$  is the initial state,
- $\delta: Q \times \Sigma \rightarrow Q$  is a state-transition function,
- $\ell: Q \rightarrow \Gamma$  is a labeling function on the states.

Definition 1 above differs from traditional DFAs in two main aspects. First, it does not define final states. This is because we use it for modeling the execution of a security protocol, which might halt at any state. Second, it includes a labeling function on the states whose output ranges over the set of output symbols  $\Gamma$ . While transition labels will be used to express the challenges exchanged in the protocol, the state labels will define the corresponding responses. We will make this precise in Definition 5 below.

Similar to normal DFAs, we assume that the state-transition function is total. When defining or drawing DFAs we will only specify the relevant transitions and, again similar to normal DFAs, we assume that specifications are completed with an implicit *trap state* that serves as the target state for all transitions that are not shown.

**Definition 2** (Generalized transition function). *Given a state-labeled DFA  $(\Sigma, \Gamma, Q, q_0, \delta, \ell)$ , we define the generalized transition function  $\hat{\delta}: \Sigma^* \rightarrow Q$  recursively as follows.*

$$\hat{\delta}(c) = \begin{cases} q_0 & \text{if } c = \varepsilon, \\ \delta(\hat{\delta}(c_1 \dots c_{n-1}), c_n) & \text{if } c = c_1 \dots c_n \quad (n \geq 1), \end{cases}$$

where  $\varepsilon$  represents the empty string.

In what follows, we denote the  $i$ th symbol of the string  $c$  by  $c_i$ . We also use the terms string and sequence interchangeably.

**Definition 3** (Generalized labeling function). *Let  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$  be a state-labeled DFA. We define the generalized labeling function  $\hat{\ell}: \Sigma^* \rightarrow \Gamma$ , for  $x \in \Sigma^*$  by:*

$$\hat{\ell}(x) = \ell(\hat{\delta}(x)).$$

Next, we provide a formal definition for a class of distance-bounding protocols based on precomputation and without final slow phase. An important feature of this type of protocols is that the prover's answers to the verifier's challenges are determined by lookup operations only. Therefore,

we will refer to this type of protocols as *lookup-based DB protocols*.

**Definition 4** (Lookup-based DB protocol). *A lookup-based DB protocol is a finite set  $P = \{A_1, A_2, \dots, A_m\}$  of state-labeled DFAs, such that for every pair  $A_i = (\Sigma_i, \Gamma_i, Q_i, q_0^i, \delta_i, \ell_i)$  and  $A_j = (\Sigma_j, \Gamma_j, Q_j, q_0^j, \delta_j, \ell_j)$  in  $P$  it holds that  $\Sigma_i = \Sigma_j$  and  $\Gamma_i = \Gamma_j$ .*

We model a protocol as a set of automata, where each automaton describes the protocol's behaviour in the fast phase. The input symbols of the automaton are the challenges and the output symbols are the corresponding responses. The structure and labeling of such an automaton follows from the calculations in the slow phase, in which, e.g., the nonces are chosen. Consequently, every possible outcome of the slow phase results in an automaton, so the number of automata in the set that describes the protocol is equal to the number of different outcomes of the slow phase. The execution of a protocol therefore consists of the (random) selection of one of the automata (the slow phase) and a run of this automaton consisting of an alternation of input and output symbols (the fast phase).

As a running example, let's consider the Hancke and Kuhn protocol. We recall that the HK protocol (see Figure 1) precomputes a bit-sequence of size  $2n$ , and all the prover's responses are based on lookup operations over the precomputed bit-sequence. We can define the HK protocol within our model as the set  $P_{HK} = \{A_0, A_1, \dots, A_{2^{2n}-1}\}$ , where, for every  $i \in \{0, \dots, 2^{2n} - 1\}$ , the automaton  $A_i = (\Sigma_i, \Gamma_i, Q_i, q_0^i, \delta_i, \ell_i)$  satisfies:

- $\Sigma_i = \Gamma_i = \{0, 1\}$ ,
- $Q_i = \{0, 1, \dots, 2n\}$  and  $q_0^i = 0$ ,
- For every  $j \in Q_i$  such that  $j \leq 2n - 2$ , and  $c \in \Sigma_i$ ,
 
$$\delta_i(j, c) = \begin{cases} j + c + 2 & \text{if } j \text{ is odd,} \\ j + c + 1 & \text{otherwise,} \end{cases}$$
- For every  $j \in Q_i$ ,  $\ell_i(j)$  is the  $j$ th least significant digit of the binary representation of  $i$ .

The number  $2^{2n}$  of state-labeled DFAs used to represent the HK protocol is not a coincidence, but the result of representing each possible  $2n$ -size bit-sequence that can be precomputed by the HK protocol. We used the following mapping between  $2n$ -size bit-sequences and automata in  $P$ : a bit-sequence  $b_1 \dots b_{2n}$  is mapped to the automaton  $A_i$  where  $i$  in base 2 is equal to  $b_1 \dots b_{2n}$ . As an example, Figure 3 shows a graphical representation of the automaton  $A_{24}$ , which represents the HK protocol with  $n = 4$  and  $b_1 \dots b_{2n} = 00011000$ . In this example, the states 4 and 5 are labeled with 1 because this is the value of both  $b_4$  and  $b_5$ , while the remaining states are labeled with 0.

**Definition 5** (Execution model). *Let  $n$  be a natural number and  $P$  a lookup-based DB protocol. A correct execution of  $P$ , up to  $n$  rounds, is a triple  $(A, C, R) \in P \times \Sigma^n \times \Gamma^n$  (indicated by  $(A, C, R) \sqsubset P$ ) such that:*

- $A$  is a sample chosen uniformly from the set  $P$ ,

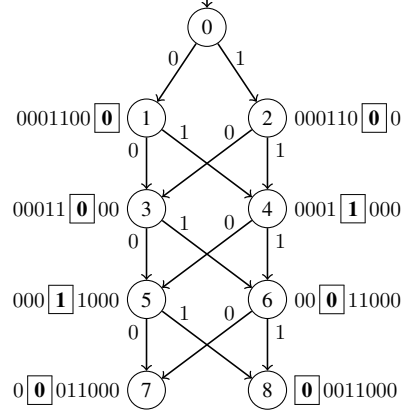


Figure 3. Automaton  $A_{24}$  for the HK protocol with 4 rounds.

- Given  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$ , challenges  $C = c_1 \dots c_n$ , and responses  $R = r_1 \dots r_n$ , it holds that  $r_i = \ell(c_1 \dots c_i)$ ,  $\forall i \in \{1, \dots, n\}$ .

The intuition behind the proposed execution model is the following. Before the start of the fast phase, the prover and the verifier agree on a *fresh* state-labeled DFA, say  $A$ . During the fast phase, the verifier sends  $n$  challenges  $c_1 \dots c_n$  and expects to receive as replies the sequence  $\hat{\ell}(c_1) \dots \hat{\ell}(c_1 \dots c_n)$ . As an example, let us consider again automaton  $A_{24}$  depicted in Figure 3. Given the input bit sequence 1100, this automaton transits over the states 2, 4, 5, and 7, whose labels are 0, 1, 1, and 0, respectively. Hence,  $(A_{24}, 1100, 0110)$  is a correct execution of the HK protocol, i.e.,  $(A_{24}, 1100, 0110) \sqsubset P_{HK}$ .

It is worth remarking that, by assuming  $A$  to be a uniformly distributed sample of the set  $P$ , our model assumes that any correct execution is equally likely to be executed. In some protocols, such as the HK protocol, that implies that the pseudo-random function is indeed random.

## 4. Properties of lookup-based DB protocols

In this section we investigate relevant properties of lookup-based DB protocols. First, we make our adversarial model explicit and provide a definition of resistance to mafia fraud. We also prove that there does not exist a lookup-based DB protocol whose resistance to mafia fraud is lower than  $\frac{1}{2^n}(1 + \frac{n}{2})$ . This result implies that the Tree-based protocol [7] is optimal in terms of resistance to mafia fraud. Further we prove a property on the probability distribution of labels in an optimal lookup-based DB protocol.

### 4.1. Mafia fraud resistance

As shown in [21], the best-known adversary strategy to perform a mafia fraud attack against distance-bounding protocols without final slow phase is the pre-ask attack. In this attack, the adversary relays all the communication between the prover and the verifier during the slow phase.

Before the beginning of the fast phase, the adversary claims to be the legitimate verifier and queries the prover  $n$  times with a sequence of challenges. The responses from the prover to these challenges are used by the adversary to later execute the fast phase with the legitimate verifier. Below, we make this intuitive definition formal.

**Definition 6** (Success probability of a pre-ask attack). *Let  $P$  be a lookup-based DB protocol and  $x \in \Sigma^n$  an input sequence. Let  $A \in P$  be a random automaton and  $y$  be an output sequence such that  $(A, x, y)$  is a correct execution. Let  $F = \{f_1, \dots, f_n\}$  be a set of functions such that  $f_i: \Sigma^i \times \Sigma^n \times \Gamma^n \rightarrow \Gamma$  for every  $i \in \{1, \dots, n\}$ .  $\Pr(F)$  denotes the probability that for a random sequence  $c_1 \dots c_n \in \Sigma^n$ , the triple  $(A, c_1 \dots c_n, z_1 \dots z_n)$  is a correct execution where  $z_i = f_i(c_1 \dots c_i, x, y)$  for every  $i \in \{1, \dots, n\}$ . The success probability of a pre-ask attack is the maximum probability  $\Pr(F)$  amongst all possible sets of functions  $F$ .*

In Definition 6, the adversary knowledge is a correct execution  $(A, x, y)$  of  $P$  where  $x$  is chosen by the adversary and  $A$  is randomly chosen in  $P$ . In other words, the adversary is able to query the prover with challenges  $x$  and receive the corresponding answers  $y$ . With this knowledge, the adversary defines a strategy to answer to the verifier's challenge. We represent such a strategy as a set of functions  $F = \{f_1, \dots, f_n\}$ . Given a sequence of challenges  $c_1 \dots c_i$  for some  $i \in \{1, \dots, n\}$ , the adversary's answer at the  $i$ th round is uniquely determined by  $f_i(c_1 \dots c_i, x, y)$ . This makes the assumption explicit that challenges are unpredictable and that the adversary replies immediately upon reception of a challenge.

## 4.2. Properties of optimal lookup-based DB protocols

As stated before, the adversary's success probability when performing mafia fraud against the Tree-based protocol is  $\frac{1}{2^n} (1 + \frac{n}{2})$ . We will prove that  $\frac{1}{2^n} (1 + \frac{n}{2})$  is indeed optimal, i.e., there does not exist a lookup-based DB protocol whose resistance to mafia fraud is lower than  $\frac{1}{2^n} (1 + \frac{n}{2})$ . For the complexity analysis we assume the protocol to have a binary set of input and output symbols, as is the case in most existing distance bounding protocols.

**Theorem 1.** *The probability value  $\frac{1}{2^n} (1 + \frac{n}{2})$  is a tight lower bound on the resistance to mafia fraud of lookup-based DB protocols with  $n$  rounds.*

*Proof.* We define the following adversary strategy to execute a pre-ask attack as in Definition 6. We consider a set of functions  $F = \{f_1, \dots, f_n\}$  such that for every  $i \in \{1, \dots, n\}$ ,  $c \in \{0, 1\}^i$ ,  $x \in \{0, 1\}^n$ , and  $y \in \{0, 1\}^n$ :

- $f_i(c, x, y) = y_i$  if  $c_1 \dots c_i = x_1 \dots x_i$ ,
- $f_i(c, x, y)$  is assigned with a random bit, otherwise.

According to the above strategy, at the  $i$ th round the adversary replies randomly unless the adversary has guessed all the verifier's challenges till the  $i$ th round, i.e.,

$c_1 \dots c_i = x_1 \dots x_i$ . Next, we compute the probability  $\Pr(F)$  of success of this strategy. Considering  $M_i$  to be the event that  $c_1 \dots c_{i-1} = x_1 \dots x_{i-1}$  and  $c_i \neq x_i$  for every  $i \in \{1, \dots, n\}$ , we obtain:

$$\Pr(F) = \sum_{i=1}^n \Pr(F|M_i) \Pr(M_i) + \Pr(F|c=x) \Pr(c=x). \quad (1)$$

Given that  $\Pr(M_i) = \frac{1}{2^i}$  and  $\Pr(c=x) = \frac{1}{2^n}$ , we get:

$$\Pr(F) = \sum_{i=1}^n \Pr(F|M_i) \frac{1}{2^i} + \Pr(F|c=x) \frac{1}{2^n}. \quad (2)$$

Taking into account that  $\Pr(F|c=x) = 1$ , Equation 2 gives:

$$\Pr(F) = \sum_{i=1}^n \Pr(F|M_i) \frac{1}{2^i} + \frac{1}{2^n}.$$

From the adversary's strategy we obtain that  $\Pr(F|M_i) = \frac{1}{2^{n-i+1}}$ , because starting from the  $i$ th round the adversary always replies randomly, which gives.

$$\Pr(F) = \sum_{i=1}^n \frac{1}{2^{n-i+1}} \frac{1}{2^i} + \frac{1}{2^n} = \frac{1}{2^n} \left(1 + \frac{n}{2}\right).$$

We conclude this proof by remarking that this lower bound is tight, because it is realized by the Tree-based protocol.  $\square$

**Definition 7** (Optimal lookup-based DB protocol). *A lookup-based DB protocol for  $n > 0$  rounds  $P$  is said to be optimal if its mafia fraud resistance is  $\frac{1}{2^n} (1 + \frac{n}{2})$ .*

Next we proceed to prove a necessary condition for optimal lookup-based DB protocols. This condition establishes that, given an input sequence  $x$  and a lookup-based DB protocol  $P$ , the labels assigned to the states reachable by  $x$  uniformly distribute in  $P$ .

**Lemma 1.** *Let  $P$  be an optimal lookup-based DB protocol with  $n > 0$  rounds. For  $i \in \{1, \dots, n\}$  and  $x \in \{0, 1\}^i$ , let  $E_0^x$  (resp.  $E_1^x$ ) be the event that given a random automaton  $(\Sigma, \Gamma, Q, q_0, \delta, \ell) \in P$  it holds that  $\hat{\ell}(x) = 0$  (resp.  $\hat{\ell}(x) = 1$ ). Then, for every  $i \in \{1, \dots, n\}$  and  $x \in \{0, 1\}^i$ ,  $\Pr(E_0^x) = \Pr(E_1^x) = \frac{1}{2}$ .*

*Proof.* Let's assume that there exists  $j \in \{1, \dots, n\}$  and  $\bar{x} \in \{0, 1\}^j$  such that  $\Pr(E_0^{\bar{x}}) \neq \frac{1}{2}$ . We define the following adversary strategy to execute a pre-ask attack as in Definition 6. We consider a set of functions  $F = \{f_1, \dots, f_n\}$  such that for every  $i \in \{1, \dots, n\}$ ,  $c \in \{0, 1\}^i$ ,  $x \in \{0, 1\}^n$ , and  $y \in \{0, 1\}^n$ :

- $f_i(c, x, y) = y_i$  if  $c_1 \dots c_i = x_1 \dots x_i$ ,
- $f_i(c, x, y) = 0$  if  $i = j \wedge c_1 \dots c_j = \bar{x}_1 \dots \bar{x}_j \neq x_1 \dots x_j \wedge \Pr(E_0^{\bar{x}}) > \frac{1}{2}$ ,

- $f_i(c, x, y) = 1$  if  $i = j \wedge c_1 \dots c_j = \bar{x}_1 \dots \bar{x}_j \neq x_1 \dots x_j \wedge \Pr(E_0^{\bar{x}}) < \frac{1}{2}$ ,
- $f_i(c, x, y)$  is assigned with a random bit, otherwise.

As in Theorem 1, we consider  $M_i$  to be the event that  $c_1 \dots c_{i-1} = x_1 \dots x_{i-1}$  and  $c_i \neq x_i$  for every  $i \in \{1, \dots, n\}$ . We thus obtain the following:

$$\Pr(F) = \sum_{i=1}^n \Pr(F|M_i) \frac{1}{2^i} + \frac{1}{2^n}. \quad (3)$$

From the adversary's strategy we obtain that  $\Pr(F|M_i) = \frac{1}{2^{n-i+1}}$  unless  $c_1 \dots c_j = \bar{x}_1 \dots \bar{x}_j$  and  $c_1 \dots c_j \neq x_1 \dots x_j$ . In this case, the probability of success of the adversary at the  $j$ th round is  $\Pr(E_0^{\bar{x}})$  if  $\Pr(E_0^{\bar{x}}) > \frac{1}{2}$  and  $1 - \Pr(E_0^{\bar{x}})$  otherwise. Therefore, we obtain that  $\Pr(F|M_i) > \frac{1}{2^{n-i+1}}$  if  $c_1 \dots c_j = \bar{x}_1 \dots \bar{x}_j \neq x_1 \dots x_j$  and  $\Pr(F|M_i) = \frac{1}{2^{n-i+1}}$  otherwise, which implies that  $\Pr(F|M_i) > \frac{1}{2^{n-i+1}}$ . Applying this result to Equation 3 gives:

$$\Pr(F) > \sum_{i=1}^n \frac{1}{2^{n-i+1}} \frac{1}{2^i} + \frac{1}{2^n} = \frac{1}{2^n} \left(1 + \frac{n}{2}\right). \quad (4)$$

Equation 4 contradicts the assumption that  $P$  is optimal, which proves that  $\Pr(E_0^{\bar{x}}) = \frac{1}{2}$ . Analogously, we can obtain that  $\Pr(E_1^{\bar{x}}) = \frac{1}{2}$ .  $\square$

### 4.3. Layered and random-labeled lookup-based DB protocols

Based on Lemma 1, we observe that the state labeling function of the DFAs in a protocol plays an important role in the protocol's resistance to pre-ask attacks. We thus define the notion of random-labeled lookup-based DB protocols, which is aimed at capturing those protocols with maximum uncertainty on the labels of the states.

**Definition 8** (Random-labeled lookup-based DB protocol). *Let  $P$  be a lookup-based DB protocol. We say that  $P$  is random-labeled if for every  $(\Sigma, \Gamma, Q, q_0, \delta, \ell) \in P$  and for every labeling function  $\ell': Q \rightarrow \Gamma$ , the automaton  $(\Sigma, \Gamma, Q, q_0, \delta, \ell')$  is also in  $P$ .*

A random-labeled lookup-based DB protocol  $P$  accounts for all possible labeling functions that can be defined on a set of states. This property is indeed satisfied by most existing distance bounding protocols. We show next that being random-labeled is a sufficient condition to satisfy the implication of Lemma 1.

**Proposition 1.** *Let  $E_0^x$  and  $E_1^x$  be the events as defined in Lemma 1. A random-labeled lookup-based DB protocol satisfies that  $\Pr(E_0^x) = \Pr(E_1^x) = \frac{1}{2}$  for every  $x \in \{0, 1\}^i$  with  $i \in \{1, \dots, n\}$ .*

*Proof.* Let  $P$  be a random-labeled protocol and  $x \in \{0, 1\}^i$  a sequence with  $i \in \{1, \dots, n\}$ . We consider a relation  $\mathcal{R}_x \subseteq P \times P$  defined as  $(A, A') \in \mathcal{R}_x$  if and only if all the following conditions hold:

- $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$ ,
- $A' = (\Sigma, \Gamma, Q, q_0, \delta, \ell')$ ,
- $\hat{\ell}(x) \neq \hat{\ell}'(x)$ ,
- $\forall q \in Q : q \neq \hat{\delta}(x) \implies \ell(q) = \ell'(q)$ .

We observe that, by definition of random-labeled, for every  $A \in P$  there exists  $A'$  such that  $(A, A') \in \mathcal{R}_x$ . Moreover,  $A'$  is unique, implying that  $\mathcal{R}_x$  is symmetric and bijective in  $P$ .

Now, let  $B_0^x$  (resp.  $B_1^x$ ) be the subset of automata in  $P$  of maximum cardinality such that  $\forall (\Sigma, \Gamma, Q, q_0, \delta, \ell) \in B_0^x : \hat{\ell}(x) = 0$  (resp.  $\forall (\Sigma, \Gamma, Q, q_0, \delta, \ell) \in B_1^x : \hat{\ell}(x) = 1$ ). Given  $(A, A') \in \mathcal{R}_x$ , we obtain that  $A \in B_0^x \iff A' \in B_1^x$ . Considering that  $\mathcal{R}_x$  is bijective, we conclude that  $|B_0^x| = |B_1^x|$ . Hence,  $\Pr(E_0^x) = \Pr(E_1^x) = \frac{1}{2}$ .  $\square$

Another property of lookup-based DB protocols that we consider in this article is that of being *layered*. Intuitively, in a layered lookup-based DB protocol with  $n$  rounds we can partition the set of states of every automaton into  $n$  subsets (layers), in such a way that all states within a layer are only reachable by input sequences of the same size.

**Definition 9** (Layered lookup-based DB protocol). *Let  $P$  be a lookup-based DB protocol. We say that  $P$  is layered if for every automaton  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell) \in P$  and for every pair  $(x, y) \in \Sigma^i \times \Sigma^j$  with  $i \neq j$ , it holds that  $\hat{\delta}(x) \neq \hat{\delta}(y)$ .*

We observe that all existing lookup-based DB protocols, except Poulidor [6], are layered and random-labeled. Figure 3 clearly shows that the example automaton of the HK protocol is layered, because the states of the  $i$ th layer, i.e.  $2i - 1$  and  $2i$ , with  $0 < i \leq 4$ , can only be reached by an input sequence of length  $i$ . The labeling function, i.e., the corresponding association from states to bits, is composed in a random way. This means that any possible bit assignment over the elements of the set  $\{1, \dots, 8\}$  may occur.

In the rest of this article we will thus focus on the analysis of layered and random-labeled lookup-based DB protocols, and we leave for future work the analysis of other types of protocols, such as Poulidor [6].

## 5. Security analysis of layered and random-labeled lookup-based DB protocols

In this section we provide an optimal adversary strategy to execute a pre-ask attack in a layered and random-labeled lookup-based DB protocol. It turns out, as expressed in Theorem 2 below, that such a strategy consists simply in sending to the verifier exactly the same responses as those obtained from the prover in the pre-ask session. As in the previous section, we assume that the sets of input and output symbols are binary.

**Theorem 2.** *Let  $P$  be a layered and random-labeled lookup-based DB protocol with  $n > 0$  rounds. Given a correct execution  $(A, x, y)$  in  $P$ , let  $F = \{f_1, \dots, f_n\}$  be a pre-ask strategy (see Definition 6) where  $f_i(c, x, y) = y_i$  for every*

$i \in \{1, \dots, n\}$  and every  $c \in \{0, 1\}^i$ . For every other pre-ask strategy  $G = \{g_1, \dots, g_n\}$  where  $g_i: \{0, 1\}^i \times \{0, 1\}^n \times \{0, 1\}^n \rightarrow \{0, 1\}$  it holds that  $\Pr(F) \geq \Pr(G)$ .

*Proof.* We define  $P^{x,y} \subseteq P$  as a subset of  $P$  such that  $A \in P^{x,y} \iff (A, x, y) \sqsubset P$ . In other words,  $P^{x,y}$  is the set of all possible automata in  $P$  that produce  $y_1 \dots y_n$  as the corresponding responses for the challenges  $x_1 \dots x_n$ .

We use  $F_i$  to denote the event that the adversary replies correctly to the first  $i$  challenges by using the pre-ask strategy  $F$ . Formally,  $F_i$  is the event that, given a random automaton  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$ , a correct execution  $(A, x, y)$ , and a random bit sequence  $c_1 \dots c_i$ ,  $f_j(c_1 \dots c_j, x, y) = \hat{\ell}(c_1 \dots c_j)$  for every  $j \in \{1, \dots, i\}$ . It should be noticed that, because  $P$  consists of  $n$  rounds,  $\Pr(F) = \Pr(F_n)$ . Analogously, we define the events  $G_1, \dots, G_n$  for a given pre-ask strategy  $G$ .

Because the verifier's challenges  $c$  and the automaton  $A$  are randomly chosen at each execution of the protocol (see Definition 6), we can compute  $\Pr(F_i)$  as follows:

$$\Pr(F_i) = \frac{\sum_{c \in \{0,1\}^i, A \in P^{x,y}} h_i(A, c, F)}{2^i |P^{x,y}|}, \quad (5)$$

where  $2^i$  is the number of input-sequences of size  $i$ ,  $|P^{x,y}|$  stands for the cardinality of  $P^{x,y}$ , and  $h_i$  is defined by:

$$h_i(A, c, F) = \begin{cases} 1 & \text{if } \forall j \in \{1, \dots, i\} \\ & \hat{\ell}(c_1 \dots c_j) = f_j(c_1 \dots c_j, x, y), \\ 0 & \text{otherwise.} \end{cases} \quad (6)$$

For every  $i \in \{1, \dots, n\}$ , we define  $h_i(A, c, G)$  and compute  $\Pr(G_i)$  analogously to Equations 6 and 5. Next we proceed by induction in order to prove that  $\Pr(F_i) \geq \Pr(G_i)$  for every  $i \in \{1, \dots, n\}$ .

Let  $P_c^{x,y}$  be a subset of  $P^{x,y}$  defined by  $\forall A = (\Sigma, \Gamma, Q, q_0, \delta, \ell) \in P^{x,y}: A \in P_c^{x,y} \iff \hat{\delta}(c) \neq \hat{\delta}(x)$ . We also consider a relation  $\mathcal{R}_c \subseteq P_c^{x,y} \times P_c^{x,y}$  defined as  $(A, A') \in \mathcal{R}_c$  if and only if all the following conditions hold:

- $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$ ,
- $A' = (\Sigma, \Gamma, Q, q_0, \delta, \ell')$ ,
- $\ell(\hat{\delta}(c)) \neq \ell'(\hat{\delta}(c))$ ,
- $\forall q \in Q: q \neq \hat{\delta}(c) \implies \ell(q) = \ell'(q)$ .

It should be noticed that the relation  $\mathcal{R}_c$  is symmetric and bijective in  $P_c^{x,y}$ , given that  $P$  is random-labeled.

Let's now analyze the case  $i = 1$ . If  $A \notin P_c^{x,y}$  and  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$ , then  $\hat{\delta}(c) = \hat{\delta}(x)$ , meaning that  $f_1(c, x, y) = \ell(c)$  and  $h_1(A, c, F) = 1 \geq h_1(A, c, G)$ . If  $A \in P_c^{x,y}$  and  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$ , we obtain that  $h_1(A, c, F) + h_1(A', c, F) = h_1(A, c, G) + h_1(A', c, G) = 1$  where  $A' = (\Sigma, \Gamma, Q, q_0, \delta, \ell')$  and  $(A, A') \in \mathcal{R}_c$ . Note that any pre-ask strategy fails either in  $A$  or in  $A'$  because  $\ell(\hat{\delta}(c)) \neq \ell'(\hat{\delta}(c))$ . This gives the following results for both strategies  $F$  and  $G$ .

$$\begin{aligned} \sum_{(A, A') \in \mathcal{R}_c} h_1(A, c, F) + h_1(A', c, F) &= 2 \sum_{A \in P_c^{x,y}} h_1(A, c, F) \\ \sum_{(A, A') \in \mathcal{R}_c} h_1(A, c, G) + h_1(A', c, G) &= 2 \sum_{A \in P_c^{x,y}} h_1(A, c, G) \end{aligned} \quad (7)$$

Considering the two cases, we conclude that  $\sum_{A \in P^{x,y}} h_1(A, c, F) \geq \sum_{A \in P^{x,y}} h_1(A, c, G)$  for every  $c \in \{0, 1\}$ , implying that  $\Pr(F_1) \geq \Pr(G_1)$ .

We define as induction hypothesis that  $\Pr(F_i) \geq \Pr(G_i)$  for every  $i \in \{1, \dots, n-1\}$ . In order to continue with an inductive reasoning, we write the function  $h_n(\cdot)$  in a recursive way as follows:

$$h_n(A, c_1 \dots c_n, F) = h_{n-1}(A, c_1 \dots c_{n-1}, F) \times \begin{cases} 1 & \text{if } f_n(c_1 \dots c_n, x, y) = \hat{\ell}(c_1 \dots c_n), \\ 0 & \text{otherwise.} \end{cases} \quad (8)$$

We analogously write  $h_n(A, c_1 \dots c_n, G)$  recursively. As in the base case, we split our analysis in two cases, depending on whether  $A \in P^{x,y}$  or not. If  $A \notin P_c^{x,y}$  then  $f_n(c, x, y) = \hat{\ell}(c)$  and  $h_n(A, c, F) = h_{n-1}(A, c_1 \dots c_{n-1}, F)$ . Given that by definition  $h_n(A, c, G) \leq h_{n-1}(A, c_1 \dots c_{n-1}, G)$ , we obtain:

$$\begin{aligned} \forall A \in P^{x,y} - P_c^{x,y}: \\ h_n(A, c, F) - h_n(A, c, G) &\geq \\ h_{n-1}(A, c_1 \dots c_{n-1}, F) - h_{n-1}(A, c_1 \dots c_{n-1}, G). \end{aligned} \quad (9)$$

Now, let's analyze the case where  $A \in P_c^{x,y}$ . Let  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$  and  $A' = (\Sigma, \Gamma, Q, q_0, \delta, \ell')$  such that  $(A, A') \in \mathcal{R}_c$ . We note that state  $\hat{\delta}(c)$  is unreachable by sequences of size smaller than  $n$ , because  $P$  is layered. On the other hand, for every state  $q$  in  $Q - \{\hat{\delta}(c)\}$  it holds that  $\ell(q) = \ell'(q)$ . Consequently, the following equalities hold for every  $(A, A') \in \mathcal{R}_c$ .

$$\begin{aligned} h_{n-1}(A, c_1 \dots c_{n-1}, F) &= h_{n-1}(A', c_1 \dots c_{n-1}, F), \\ h_{n-1}(A, c_1 \dots c_{n-1}, G) &= h_{n-1}(A', c_1 \dots c_{n-1}, G). \end{aligned} \quad (10)$$

As in the base case, we observe that any pre-ask strategy fails either in  $A$  or in  $A'$ , given that  $\ell(\hat{\delta}(c)) \neq \ell'(\hat{\delta}(c))$ . This observation and Equation 10 lead to the following result.

$$\begin{aligned} \sum_{A \in P_c^{x,y}} h_n(A, c, F) + h_n(A', c, F) &= \\ 2h_{n-1}(A, c_1 \dots c_{n-1}, F), \\ \sum_{A \in P_c^{x,y}} h_n(A, c, G) + h_n(A', c, G) &= \\ 2h_{n-1}(A, c_1 \dots c_{n-1}, F). \end{aligned}$$



Because  $\mathcal{R}_c$  is bijective and symmetric we obtain:

$$\begin{aligned} \sum_{A \in P_c^{x,y}} h_n(A, c, F) &= h_{n-1}(A, c_1 \dots c_{n-1}, F), \\ \sum_{A \in P_c^{x,y}} h_n(A, c, G) &= h_{n-1}(A, c_1 \dots c_{n-1}, F). \end{aligned} \quad (11)$$

Equations 9 and 11 together give:

$$\begin{aligned} \sum_{A \in P^{x,y}} h_n(A, c, F) - h_n(A, c, G) &\geq \\ \sum_{A \in P^{x,y}} h_{n-1}(A, c_1 \dots c_{n-1}, F) - h_{n-1}(A, c_1 \dots c_{n-1}, G). \end{aligned} \quad (12)$$

Considering the induction hypothesis, we finally obtain that  $\sum_{A \in P^{x,y}} h_n(A, c, F) - h_n(A, c, G) \geq 0$  for every  $c \in \{0, 1\}^n$ . This yields  $\Pr(F_n) \geq \Pr(G_n)$ , which is the required result.  $\square$

From now on, we will use  $\mathcal{F}(P)$  to denote the success probability of a pre-ask attack in protocol  $P$ , i.e.  $\mathcal{F}(P) = \Pr(F)$  where  $F$  is defined as in Theorem 2.

## 6. A family of protocols that are arbitrarily close to optimal

We have proven that  $\frac{1}{2^n} (1 + \frac{n}{2})$  is a tight lower bound on the resistance to mafia fraud of lookup-based DB protocols with  $n$  rounds. Only the Tree-based approach achieves such lower bound, at the cost of an exponential number of states, though. In this section we introduce a subclass of lookup-based DB protocols that contains protocols whose resistance to pre-ask attacks is arbitrarily close to the above-mentioned optimal bound.

### 6.1. Uniform lookup-based DB protocols

Protocols within the proposed subclass are layered and random-labeled. In addition, they satisfy an additional property that we call *uniformity*. The property is related to the possibility for an adversary to guess the correct states in an execution, i.e. to have certainty on the responses. We formally define the concept of uniformity and later on we explain our intuition behind it.

**Definition 10** (Uniformity). *Let  $P$  be a layered and random-labeled lookup-based DB protocol with  $n > 0$  rounds. We say that  $P$  is  $u$ -uniform with  $u \in \{1, \dots, n\}$ , if for every  $k \in \{1, \dots, n\}$  and for every  $x, y \in \{0, 1\}^k$  it holds that  $\hat{\delta}(x) = \hat{\delta}(y) \iff (k \leq u \wedge x = y) \vee (k > u \wedge x_{k-u+1}x_{k-u+2} \dots x_k = y_{k-u+1}y_{k-u+2} \dots y_k)$ .*

In other words,  $u$ -uniformity means that two input sequences of length  $k$  reach the same state if and only if the

last  $u$  symbols (or  $k$  symbols if  $k \leq u$ ) of the two sequences are equal.

Intuitively the notion of uniformity is related to the possibility for an adversary to predict the correct states in the pre-ask session. Suppose the adversary chooses a challenge sequence  $x_1 \dots x_n$  to query the prover. Also, consider  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell)$  to be the selected automaton for the protocol execution, which is unknown to the adversary. Suppose now  $y_1 \dots y_n$  are the verifier's challenges. Let's call  $q_1 \dots q_n$  and  $q'_1 \dots q'_n$  the sequences of states reached by both challenge sequences, i.e.  $q_i = \hat{\delta}(x_1 \dots x_i)$  and  $q'_i = \hat{\delta}(y_1 \dots y_i)$  for every  $i \in \{1, \dots, n\}$ . Intuitively, the more elements  $q_1 \dots q_n$  and  $q'_1 \dots q'_n$  have in common, the more vulnerable the protocol becomes, since the adversary has the responses for those states. In the case of a  $u$ -uniform protocol, for the adversary to reach the correct state, let's say at round  $i$ , he needs to guess all the  $u$  (or  $i$  if  $i \leq u$ ) last verifier's challenges in advance. So, the higher the uniformity value  $u$ , the harder it gets for the adversary to make the correct guesses.

We say that a protocol is *uniform* if it is  $u$ -uniform for some  $u$ . We will refer to  $u$  as the *uniformity value* of a protocol. It is ensured that this uniformity value is unique because the set of input symbols has more than one element. Next, we show that HK [14] and Tree-based [7] are 1-uniform and  $n$ -uniform, respectively. The proofs that they are layered and random-labeled are omitted since they belong to our family of protocols that will be defined later and for which we will provide a formal proof (see Section 6.3).

**Proposition 2.** *The HK protocol is 1-uniform.*

*Proof.* In this proof we will use the definition of the HK protocol provided in Section 3.

Let  $x_1 \dots x_k$  and  $y_1 \dots y_k$  be two binary sequences of length  $k \in \{1, \dots, n\}$ . Let  $q_x, q_y \in Q$  be two states such that  $q_x \in \hat{\delta}(x_1 \dots x_{k-1})$  and  $q_y \in \hat{\delta}(y_1 \dots y_{k-1})$ . Notice that if  $k = 1$  then  $q_x = q_y = q_0$ . Hence,

$$\begin{aligned} \hat{\delta}(x_1 \dots x_k) &= \hat{\delta}(y_1 \dots y_k) \\ \iff \delta(q_x, x_k) &= \delta(q_y, y_k) \\ \iff (q_x + x_k + 1 + q_x \pmod{2}) \pmod{2} &= (q_y + y_k + 1 + q_y \pmod{2}) \pmod{2}. \end{aligned}$$

But,  $(q + q \pmod{2} + 1) \pmod{2} = 1$  for every  $q \in \mathbb{N}$ . Therefore,

$$\begin{aligned} (q_x + x_k + 1 + q_x \pmod{2}) \pmod{2} &= (q_y + y_k + 1 + q_y \pmod{2}) \pmod{2} \\ \iff x_k \pmod{2} &= y_k \pmod{2} \\ \iff x_k &= y_k. \end{aligned}$$

Finally,  $\hat{\delta}(x_1 \dots x_k) = \hat{\delta}(y_1 \dots y_k) \iff x_k = y_k$ .  $\square$

**Proposition 3.** *The Tree-based protocol with  $n > 0$  rounds is  $n$ -uniform.*

*Proof.* Consider the following model for the Tree-based protocol  $P = \{A_0, A_1, \dots, A_N\}$  where  $A_i =$

$(\{0, 1\}, \{0, 1\}, Q, q_0, \delta, \ell_i)$  such that  $Q = \{0, 1, \dots, 2^{n+1} - 2\}$ ,  $q_0 = 0$ ,  $\delta(d, c) = 2d + c + 1$ , and  $\ell_i(q)$  is the  $q$ th bit of the binary representation of  $i$ . In addition,  $N = 2^{|Q|-1} - 1 = 2^{2^{n+1}-3} - 1$ .

Let  $x_1 \dots x_k$  and  $y_1 \dots y_k$  be two binary sequences of length  $k \in \{1, \dots, n\}$ . Let  $q_x, q_y \in Q$  be two states such that  $q_x \in \hat{\delta}(x_1 \dots x_{k-1})$  and  $q_y \in \hat{\delta}(y_1 \dots y_{k-1})$ . Notice that if  $k = 1$  then  $q_x = q_y = q_0$ . Then:

$$\begin{aligned} & \hat{\delta}(x_1 \dots x_k) = \hat{\delta}(y_1 \dots y_k) \\ \iff & \delta(q_x, x_k) = \delta(q_y, y_k) \\ \iff & 2q_x + x_k + 1 = 2q_y + y_k + 1. \end{aligned}$$

Now, let us prove that  $2q_x + x_k + 1 = 2q_y + y_k + 1 \iff q_x = q_y \wedge x_k = y_k$ . The implication from right to left is trivial, so we proceed by proving the implication from left to right. Indeed,

$$\begin{aligned} & 2q_x + x_k + 1 = 2q_y + y_k + 1 \\ \implies & 2q_x + x_k + 1 \pmod{2} = 2q_y + y_k + 1 \pmod{2} \\ \implies & x_k \pmod{2} = y_k \pmod{2} \implies x_k = y_k. \end{aligned}$$

Hence, if  $2q_x + x_k + 1 = 2q_y + y_k + 1$  and  $x_k = y_k$  then  $q_x = q_y$ . Therefore,

$$\begin{aligned} q_x = q_y \\ \iff & \delta(\hat{\delta}(x_1 \dots x_{k-2}), x_{k-1}) = \delta(\hat{\delta}(y_1 \dots y_{k-2}), y_{k-1}). \end{aligned}$$

Analogously, we have:

$$\begin{aligned} & \delta(\hat{\delta}(x_1 \dots x_{k-2}), x_{k-1}) = \delta(\hat{\delta}(y_1 \dots y_{k-2}), y_{k-1}) \\ \iff & \hat{\delta}(x_1 \dots x_{k-2}) = \hat{\delta}(y_1 \dots y_{k-2}) \wedge x_{k-1} = y_{k-1} \end{aligned}$$

and so on, until reaching  $x_1 = y_1$ . Finally,  $\hat{\delta}(x_1 \dots x_k) = \hat{\delta}(y_1 \dots y_k) \iff x_1 \dots x_k = y_1 \dots y_k$ .  $\square$

Next we provide a closed formula to compute the resistance of uniform distance bounding protocols to pre-ask attacks. Again, for the sake of simplicity, we assume that the sets of input and output symbols are binary.

## 6.2. Pre-ask attacks in uniform protocols

To compute the highest success probability of a pre-ask attack in  $u$ -uniform protocols we will use the results from Theorem 2. That is to say, we will compute the adversary's success probability when executing the optimal pre-ask strategy defined in Theorem 2. We recall that such a strategy consists in replying to the verifier's challenges with the answers received from the prover.

**Theorem 3.** *Let  $P$  be a  $u$ -uniform lookup-based DB protocol for  $n > 0$  rounds. Then the success probability of a pre-ask attack is  $\mathcal{F}(P) = R_n$ , where  $R_0 = 1$  and*

$$R_i = \frac{1}{2^i} + \sum_{j=0}^{i-1} \frac{R_{i-j-1}}{2^{j+\min(u, j+1)+1}},$$

for  $i \in \{1, \dots, n\}$ .

*Proof.* Let  $x \in \{0, 1\}^n$  be an input sequence representing the adversary's challenges to query the prover in the pre-ask phase. Let  $A = (\Sigma, \Gamma, Q, q_0, \delta, \ell) \in P$  and  $x' \in \{0, 1\}^n$  be a random automaton and a random bit sequence, respectively. Let  $y, y' \in \{0, 1\}^n$  be two binary sequences such that  $(A, x, y) \sqsubset P$  and  $(A, x', y') \sqsubset P$ . The input sequence  $x'$  represents the one picked (randomly) by the verifier to execute the fast phase.

According to Theorem 2, we have that  $\mathcal{F}(P) = \Pr(y = y')$ . In order to compute  $\Pr(y = y')$ , consider the following events:

- $S_i$  is the event that  $y_1 \dots y_i = y'_1 \dots y'_i$  for every  $i \in \{1, \dots, n\}$ .
- $M_{i,j}$  is the event that  $x_{i-j+1} \dots x_i = x'_{i-j+1} \dots x'_i \wedge x_{i-j} \neq x'_{i-j}$  for every  $i \in \{1, \dots, n\}$  and  $j \in \{0, \dots, i-1\}$ . Note that  $M_{i,0}$  becomes  $x_i \neq x'_i$ .
- $E_i$  is the event that  $x_1 \dots x_i = x'_1 \dots x'_i$  for every  $i \in \{1, \dots, n\}$ . Notice that  $E_i$  occurs if none of the events  $M_{i,i-1}$  do, which means that  $\Pr(E_i \vee M_{i,0} \vee \dots \vee M_{i,i-1}) = 1$ .

Our goal is to compute the values of  $\Pr(S_i)$  and in particular  $\Pr(S_n)$ . By the law of total probability we have:

$$\begin{aligned} \Pr(S_i) &= \Pr(S_i|E_i) \Pr(E_i) + \sum_{j=0}^{i-1} \Pr(S_i|M_{i,j}) \Pr(M_{i,j}) \\ &= \frac{1}{2^i} + \sum_{j=0}^{i-1} \Pr(S_i|M_{i,j}) \Pr(M_{i,j}), \end{aligned} \quad (13)$$

because  $\Pr(S_i|E_i) = 1$  and  $\Pr(E_i) = \frac{1}{2^i}$ . Moreover, for every  $i \in \{1, \dots, n\}$  and  $j \in \{1, \dots, i-1\}$ , since the sequence  $x'$  is chosen randomly and its bits are independent, we have that:

$$\begin{aligned} \Pr(M_{i,j}) &= \Pr(x_{i-j} \neq x'_{i-j}) \times \prod_{k=i-j+1}^i \Pr(x_k = x'_k) \\ &= \frac{1}{2} \times \frac{1}{2^j} = \frac{1}{2^{j+1}}. \end{aligned} \quad (14)$$

Observe that  $\Pr(M_{i,0}) = \Pr(x_i \neq x'_i) = \frac{1}{2}$ . Now let's compute the values  $\Pr(S_i|M_{i,j})$  for  $i \in \{1, \dots, n\}$  and  $j \in \{0, \dots, i-1\}$ . Given  $i$  and  $j$ , assume  $M_{i,j}$  occurs, i.e. the input sequences  $x_1 \dots x_i$  and  $x'_1 \dots x'_i$  have the same last  $j$  symbols. So, if  $j \geq u$ , because of the uniformity property, we have that:

$$\begin{aligned} & \hat{\delta}(x_1 \dots x_{i-j}) \neq \hat{\delta}(x'_1 \dots x'_{i-j}), \\ & \hat{\delta}(x_1 \dots x_{i-j+1}) \neq \hat{\delta}(x'_1 \dots x'_{i-j+1}), \\ & \dots \\ & \hat{\delta}(x_1 \dots x_{i-j+u-1}) \neq \hat{\delta}(x'_1 \dots x'_{i-j+u-1}), \end{aligned} \quad (15)$$

and

$$\begin{aligned} & \hat{\delta}(x_1 \dots x_{i-j+u}) = \hat{\delta}(x'_1 \dots x'_{i-j+u}), \\ & \hat{\delta}(x_1 \dots x_{i-j+u+1}) = \hat{\delta}(x'_1 \dots x'_{i-j+u+1}), \\ & \dots \\ & \hat{\delta}(x_1 \dots x_i) = \hat{\delta}(x'_1 \dots x'_i). \end{aligned} \quad (16)$$

From Equations 15 and 16 and given that the protocol is random-labeled we derive that, for every  $k \in \{i-j, \dots, i\}$ :

$$\Pr(y_k = y'_k | M_{i,j}) = \begin{cases} \frac{1}{2} & \text{if } k \leq i-j+u-1, \\ 1 & \text{otherwise.} \end{cases}$$

This leads to:

$$\Pr(y_{i-j} \dots y_i = y'_{i-j} \dots y'_i | M_{i,j}) = \frac{1}{2^u}. \quad (17)$$

On the other hand, if  $j < u$  then  $\hat{\delta}(x_1 \dots x_k) \neq \hat{\delta}(x'_1 \dots x'_k)$  for every  $k \in \{i-j, i\}$  and consequently:

$$\Pr(y_{i-j} \dots y_i = y'_{i-j} \dots y'_i | M_{i,j}) = \frac{1}{2^{j+1}}. \quad (18)$$

Furthermore, the event  $S_{i-j-1}$  and the event that  $y_{i-j} \dots y_i$  is equal to  $y'_{i-j} \dots y'_i$  are independent, given the uniformity property and that  $x_{i-j} \neq x'_{i-j}$ . This gives:

$$\begin{aligned} \Pr(S_i | M_{i,j}) &= \Pr(S_{i-j-1} | M_{i,j}) \\ &\times \Pr(y_{i-j} \dots y_i = y'_{i-j} \dots y'_i | M_{i,j}). \end{aligned} \quad (19)$$

Equations 17, 18 and 19 give:

$$\Pr(S_i | M_{i,j}) = \frac{\Pr(S_{i-j-1} | M_{i,j})}{2^{\min(u,j+1)}}. \quad (20)$$

Observe now that the events  $M_{i,j}$  and  $S_{i-j-1}$  are independent, which means that  $\Pr(S_{i-j-1} | M_{i,j}) = \Pr(S_{i-j-1})$ . By applying this result to Equation 20 we obtain:

$$\Pr(S_i | M_{i,j}) = \frac{\Pr(S_{i-j-1})}{2^{\min(u,j+1)}}. \quad (21)$$

Finally, from Equations 13, 14 and 21 and by applying the substitution  $R_i = \Pr(S_i)$  we obtain the expected recursive formula. We conclude this proof by remarking that  $\mathcal{F}(P) = \Pr(S_n) = R_n$ .  $\square$

A consequence of this theorem is that, in uniform protocols, the adversary has no advantage in selecting the challenges to query the prover. In the next corollaries we show, by using the previous theorem, a security computation in terms of pre-ask attacks for the mentioned HK and Tree-based protocols.

**Corollary 1.** *Let  $P$  be the HK-protocol for  $n > 0$  rounds. Then  $\mathcal{F}(P) = \left(\frac{3}{4}\right)^n$ .*

*Proof.* Since the HK protocol is 1-uniform (see Proposition 2), we have:

$$R_i = \frac{1}{2^i} + \sum_{j=0}^{i-1} \frac{R_{i-j-1}}{2^{j+2}}.$$

By multiplying the previous equation by  $2^i$  we have:

$$\begin{aligned} 2^i R_i &= 1 + \sum_{j=0}^{i-1} 2^{i-j-2} R_{i-j-1} \\ &= 1 + \frac{1}{2} \sum_{j=0}^{i-1} 2^{i-j-1} R_{i-j-1}. \end{aligned}$$

By substituting  $k = i-j-1$ , the last equation can be written as  $2^i R_i = 1 + \frac{1}{2} \sum_{k=0}^{i-1} 2^k R_k$ , since  $i-j-1$  goes from 0 to  $i-1$ . Now, by applying the substitution  $B_i = 2^i R_i$  we obtain, for every  $i \in \{1, \dots, n\}$ :

$$B_i = 1 + \frac{1}{2} \sum_{k=0}^{i-1} B_k, \quad (22)$$

and for every  $i \in \{0, \dots, n-1\}$ :

$$B_{i+1} = 1 + \frac{1}{2} \sum_{k=0}^i B_k. \quad (23)$$

Now, by subtracting Equation 22 from Equation 23 we obtain

$$B_{i+1} - B_i = \frac{1}{2} B_i, \forall i \in \{0, \dots, n-1\},$$

which implies that  $B_{i+1} = \frac{3}{2} B_i$  and given that  $B_0 = 1$ , we obtain  $B_i = \left(\frac{3}{2}\right)^i$ . Therefore  $R_i = \frac{B_i}{2^i} = \left(\frac{3}{4}\right)^i$  and  $\mathcal{F}(P) = R_n = \left(\frac{3}{4}\right)^n$ .  $\square$

**Corollary 2.** *Let  $P$  be the Tree-based protocol for  $n > 0$  rounds. Then  $\mathcal{F}(P) = \frac{1}{2^n} \left(1 + \frac{n}{2}\right)$ .*

*Proof.* Since the Tree-based protocol is  $n$ -uniform (see Proposition 3), we have:

$$R_i = \frac{1}{2^i} + \sum_{j=0}^{i-1} \frac{R_{i-j-1}}{2^{2j+2}}.$$

By multiplying the previous equation by  $4^i$  we obtain:

$$\begin{aligned} 4^i R_i &= 2^i + \sum_{j=0}^{i-1} 4^{i-j-1} R_{i-j-1} \\ &= 2^i + \sum_{k=0}^{i-1} 4^k R_k. \end{aligned}$$

Hence, let  $B_i = 4^i R_i$ , then:

$$B_i = 2^i + \sum_{k=0}^{i-1} B_k, \forall i \in \{1, \dots, n\}, \quad (24)$$

and,

$$B_{i+1} = 2^{i+1} + \sum_{k=0}^i B_k, \forall i \in \{0, \dots, n-1\}. \quad (25)$$

Therefore, by subtracting Equation 24 from Equation 25, for every  $i \in \{0, \dots, n-1\}$ , we have that  $B_{i+1} - B_i = 2^i + B_i$  and consequently  $B_{i+1} = 2B_i + 2^i$  and  $\frac{B_{i+1}}{2^{i+1}} = \frac{B_i}{2^i} + \frac{1}{2}$ .

Now, by setting  $D_i = \frac{B_i}{2^i}$  we have that  $D_{i+1} = D_i + \frac{1}{2}$  and therefore  $D_i = \frac{i}{2} + D_0$ . Since  $R_0 = 1$ , we have that  $B_0 = 1$  and  $D_0 = 1$ . Therefore,  $B_i = 2^i \left(1 + \frac{i}{2}\right)$  which implies that  $R_i = \frac{1}{2^i} \left(1 + \frac{i}{2}\right)$ . Finally,  $\mathcal{F}(P) = R_n = \frac{1}{2^n} \left(1 + \frac{n}{2}\right)$ .  $\square$

Next we prove that the resistance to pre-ask attacks of uniform lookup-based DB protocols monotonically depends on their uniformity value.

**Theorem 4.** *Let  $P_u$  and  $P_v$  be two uniform protocols with uniformity values  $u$  and  $v$ , respectively. Assume that these protocols have the same number of rounds  $n > 0$ . Then  $u \leq v \implies \mathcal{F}(P_u) \geq \mathcal{F}(P_v)$ .*

*Proof.* We introduce the notation

$$R_i^u = \frac{1}{2^i} + \sum_{j=0}^{i-1} \frac{R_{i-j-1}^u}{2^{j+\min(u,j+1)+1}} \quad (26)$$

to refer to the recursive equation in Theorem 3 for  $P_u$ . Analogously, we use  $R_i^v$  for  $P_v$ . Assuming  $u \leq v$ , we proceed by induction over  $i$  to prove that  $R_i^u \geq R_i^v$  for every  $i \in \{0, \dots, n\}$  and in particular that  $R_n^u \geq R_n^v$ , i.e.  $\mathcal{F}(P_u) \geq \mathcal{F}(P_v)$ .

The base case  $i = 0$  trivially holds, given that  $R_0^u = R_0^v = 1$ . Now, let us assume that  $R_j^u \geq R_j^v$  (induction hypothesis) for every  $j < i$ . From  $u \leq v$  it follows that  $\min(u, j+1) \leq \min(v, j+1)$  for every  $j \in \{1, \dots, n\}$  and consequently  $2^{\min(u,j+1)} \leq 2^{\min(v,j+1)}$ . This implies that

$$\frac{1}{2^{j+\min(u,j+1)+1}} \geq \frac{1}{2^{j+\min(v,j+1)+1}}. \quad (27)$$

Besides, from the induction hypothesis, for every  $j \in \{0, \dots, i-1\}$  we obtain that

$$R_{i-j-1}^u \geq R_{i-j-1}^v. \quad (28)$$

From Equations 26, 27 and 28 we obtain that  $R_i^u \geq R_i^v$  and in particular  $R_n^u \geq R_n^v$ .  $\square$

For a given  $n > 0$ , consider  $f: \{1, \dots, n\} \rightarrow [\frac{1}{2^n}(1 + \frac{n}{2}), (\frac{3}{4})^n]$  to be a function such that  $f(u) = \mathcal{F}(P_u)$  where  $P_u$  is a  $u$ -uniform lookup-based DB protocol. Theorem 4 demonstrates that  $f$  is decreasing and approaches  $\frac{1}{2^n}(1 + \frac{n}{2})$  when  $u$  approaches  $n$ . Based on these results, we can affirm that the closer the uniformity value gets to  $n$  (resp. 1) the lower (resp. higher) the success probability of a pre-ask attack. In particular,  $n$ -uniform protocols (such as Tree-based) are optimal within this class, whereas 1-uniform (such as HK) perform worst.

In the following, we model a family of uniform lookup-based DB protocols and describe them in standard cryptographic notation. Also, we show that for every uniformity value, there exists at least one protocol within our proposed class. This means that, for every  $u \leq n$ , where  $n$  is the number of rounds, we provide a construction of a  $u$ -uniform protocol. This affirms that we can build a protocol with mafia-fraud resistance arbitrarily close to optimal, by defining its uniformity value and using our model. The proposed protocols require significantly fewer states than the Tree-based approach.

### 6.3. A family of uniform protocols

Let  $n > 0$  and  $u \in \{1, \dots, n\}$  be two integer numbers. Consider the following construction of protocol  $P$  for  $n$  rounds.  $P = \{A_0, A_2, \dots, A_N\}$  such that  $A_i = (\{0, 1\}, \{0, 1\}, Q, q_0, \delta, \ell_i)$ , where

- $Q = \{(i, d) \mid 0 \leq i \leq n \wedge 0 \leq d < \min(2^u, 2^i)\}$ ,
- $q_0 = (0, 0)$ ,
- $\delta((i, d), c) = (i + 1, (2d + c) \pmod{2^u})$  for every  $c \in \{0, 1\}$  and  $(i, d) \in Q$  such that  $i < n$ ,
- $N = 2^{|Q|-1} - 1$ , and
- for every  $j \in \{1, \dots, N\}$ ,  $\ell_j(q)$  is the  $k$ th bit in the binary representation of  $j$  and  $k$  is the position of  $q$  in  $Q - \{q_0\}$ .

In this construction, we define  $Q$  as a set of pairs of integers. Each pair  $(i, d)$  represents a state, in layer  $i$ , where  $d$  is the position in this layer. For two binary strings to share the last  $u$  bits, their decimal representations have to leave the same remainder when divided by  $2^u$ . Based on this property, we build our state transition function. The expression  $\delta((i, d), c) = (i + 1, (2d + c) \pmod{2^u})$  stands for this idea. Notice that  $d(c_1 \dots c_i) = 2d(c_1 \dots c_{i-1}) + c_i$ , where  $d(\cdot)$  represents a function that converts binary strings into integers (left-to-right order). We use  $d(\cdot)$  here as a function since it relates the second value of the pairs representing the states. Moreover, for every  $j \in \{1, \dots, u\}$  and  $c \in \{0, 1\}^j$  the values  $d(c)$  have at most  $2^j$  different remainders when divided by  $2^u$ , this explains our upper bound for  $d$  in the definition of  $Q$ . The last two rules in our construction represent the random-labeling property, although in practice this is achieved by generating a distribution of random bits over the set of states. A formal proof of these ideas is shown in the next lemma.

**Lemma 2.** *The proposed protocol is  $u$ -uniform.*

*Proof.* We first prove that  $P$  is layered and random-labeled. Because of the definition of  $\delta$ , for every pair  $x, y \in \{0, 1\}^i \times \{0, 1\}^j$  with  $i \neq j$  we have that  $\hat{\delta}(x) = (i, a_x)$  and  $\hat{\delta}(y) = (j, a_y)$ , where  $a_x$  and  $a_y$  are integer numbers (they are irrelevant for our proof). Then  $(i, a_x) \neq (j, a_y)$  and  $\hat{\delta}(x) \neq \hat{\delta}(y)$ . Therefore  $P$  is layered.

To show the random-labeling property, consider any labeling function  $\ell: Q - \{q_0\} \rightarrow \{0, 1\}$ . Let  $B = b_1 b_2 \dots b_{|Q|-1}$  be a binary string such that  $b_i = \ell(q_i)$  for every  $i \in \{1, \dots, |Q| - 1\}$ . We recall that  $q_0$  does not require a label since it is never used for replies. Let  $D = \sum_{i=1}^{|Q|-1} 2^{i-1} b_i$  be an integer number, i.e. the decimal representation of  $B$ . Then, given that  $N = 2^{|Q|-1} - 1$  we have that  $D \in \{0, \dots, N\}$  and, because of our construction,  $\ell_D = \ell$ . This proves that for any  $\ell$ , it holds that  $(\{0, 1\}, \{0, 1\}, Q, q_0, \delta, \ell) \in P$ . Every labeling function is unique since it is related to a unique integer number in  $D$ . This states that  $P$  is indeed a set.

Next, we demonstrate that  $P$  satisfies the uniformity property. Let  $k \in \{1, \dots, n\}$  and let  $x = x_1 \dots x_k, y = y_1 \dots y_k$  be two bit sequences of length  $k$ . Because of

our definition of the state-transition function  $\delta$ , we derive that  $\hat{\delta}(x) = (k, S_x(\text{mod } 2^u))$  and  $\hat{\delta}(y) = (k, S_y(\text{mod } 2^u))$  where

$$S_x = \sum_{i=1}^k 2^{k-i} x_i,$$

$$S_y = \sum_{i=1}^k 2^{k-i} y_i.$$

In the previous two equations,  $S_x$  and  $S_y$  are the decimal representations of the bit strings  $x$  and  $y$ , respectively. Hence,

$$\hat{\delta}(x) = \hat{\delta}(y) \iff S_x(\text{mod } 2^u) = S_y(\text{mod } 2^u).$$

Now we have two cases. If  $k \leq u$  then we have  $S_x < 2^u$  and  $S_y < 2^u$  and, consequently,

$$\begin{aligned} \hat{\delta}(x) &= \hat{\delta}(y) \\ \iff S_x(\text{mod } 2^u) &= S_y(\text{mod } 2^u) \\ \iff S_x &= S_y \\ \iff x &= y. \end{aligned}$$

On the other hand, if  $k > u$  we can write  $S_x$  (and analogously  $S_y$ ) in the following way:

$$\begin{aligned} S_x &= \sum_{i=1}^{k-u} 2^{k-i} x_i + \sum_{i=k-u+1}^k 2^{k-i} x_i \\ &= 2^u \left( \sum_{i=1}^{k-u} 2^{k-i-u} x_i \right) + \sum_{i=k-u+1}^k 2^{k-i} x_i. \end{aligned}$$

Since  $k - i - u \geq 0$  for every  $i \in \{1, \dots, k - u\}$ , all the elements in the first sum are integers. This implies that  $S_x(\text{mod } 2^u) = S'_x(\text{mod } 2^u)$  and  $S_y(\text{mod } 2^u) = S'_y(\text{mod } 2^u)$ , where

$$S'_x = \sum_{i=k-u+1}^k 2^{k-i} x_i,$$

$$S'_y = \sum_{i=k-u+1}^k 2^{k-i} y_i.$$

Therefore,

$$\begin{aligned} \hat{\delta}(x) &= \hat{\delta}(y) \\ \iff S_x(\text{mod } 2^u) &= S_y(\text{mod } 2^u) \\ \iff S'_x(\text{mod } 2^u) &= S'_y(\text{mod } 2^u). \end{aligned}$$

Given that  $k - i < u$  for every  $i \in \{k - u + 1, \dots, k\}$ , we deduce that both  $S'_x$  and  $S'_y$  are less than  $2^u$ . This implies that

$$\begin{aligned} \hat{\delta}(x) &= \hat{\delta}(y) \\ \iff S_x(\text{mod } 2^u) &= S_y(\text{mod } 2^u) \\ \iff S'_x(\text{mod } 2^u) &= S'_y(\text{mod } 2^u) \\ \iff S'_x &= S'_y \\ \iff x_{k-u+1} \dots x_k &= y_{k-u+1} \dots y_k. \end{aligned}$$

Finally, from both cases we obtain the necessary and sufficient condition stated in Definition 10.  $\square$

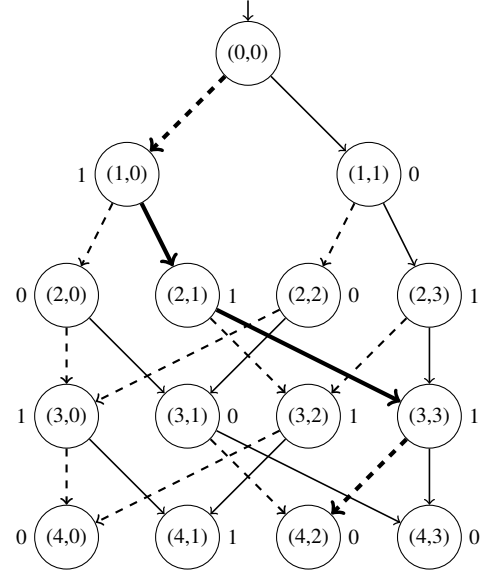


Figure 4. An automaton representing an instantiation of a 2-uniform lookup-based DB protocol for  $n = 4$  rounds. Dashed and solid lines represent transitions when the input symbol is 0 and 1, respectively. With bold lines we highlight an execution with challenge sequence 0110 and responses 1110.

The intuition behind the above construction is that the set of states  $Q$  can be partitioned into  $n$  sets  $Q_0, Q_1, \dots, Q_n$  such that  $i \in \{0, \dots, n\}$  where  $Q_i = \{(i, d) \mid 0 \leq d < \min(2^u, 2^i)\}$ . The transition function only connects states in  $Q_i$  with states in  $Q_{i+1}$ . The corresponding state for a sequence of input symbols  $c_1 \dots c_i \in \{0, 1\}^i$  is the  $k$ -th state in the layer  $i$ , where  $k$  is the remainder of the division of  $\sum_{j=1}^i 2^{j-1} c_j$  by  $2^u$ . The composition of the labeling functions basically represents a random distribution of bits over the set of states  $Q$ .

An example of an automaton for a 2-uniform protocol following the model above is depicted in Figure 4. Next, we describe our protocol in standard cryptographic notation for distance-bounding protocols. Concretely, the proposed protocol consists of the following phases:

**Initialization phase.** The prover and the verifier agree on the following parameters:

- A shared key  $x$ .
- An integer number  $m > 0$  which represents the length of the nonces.
- An integer number  $n > 0$  which represents the number of rounds.
- An integer number  $u \in \{1, \dots, n\}$  which represents the uniformity value.
- A pseudo random function  $g$ .
- A threshold for the round-trip-time  $\Delta t_{max}$ .

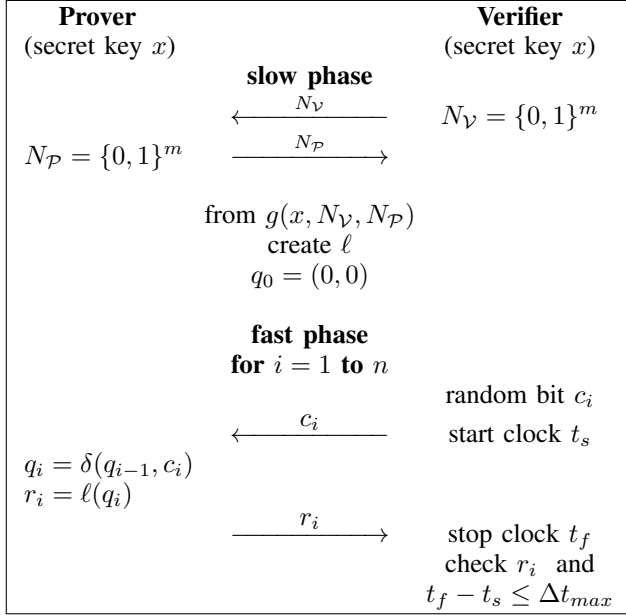


Figure 5. The proposed  $u$ -uniform lookup-based DB protocol.

**Slow phase.** Both parties generate nonces,  $N_{\mathcal{P}}$  for the prover and  $N_{\mathcal{V}}$  for the verifier. The value  $N_{\mathcal{V}}$  is sent to the prover which constructs the labeling function from  $g(x, N_{\mathcal{V}}, N_{\mathcal{P}})$ . Then, the prover sends the nonce  $N_{\mathcal{P}}$  to the verifier and the latter also computes the function  $g(x, N_{\mathcal{V}}, N_{\mathcal{P}})$  to agree with the prover on the labeling function.

- *Constructing the labeling function  $\ell$ :* The shared pseudo-random function  $g$  outputs  $n$  registers  $B^1 || B^2 || \dots || B^n$  such that  $B^i$  is a  $2^{\min(u, i)}$ -bit string. Then  $\ell((i, d)) = B_d^i$  for every  $i \in \{1, \dots, n\}$  and  $0 \leq d < \min(2^u, 2^i)$ .

**Fast phase.** This phase is composed of  $n$  rounds numbered from 1 to  $n$ . At the  $i$ -th round, the verifier sends a challenge bit  $c_i$  to the prover which moves from the previous state  $q_{i-1}$  to the next one  $q_i = \delta(q_{i-1}, c_i)$  and replies with the corresponding bit  $\ell(q_i)$ .

**Verification phase.** The protocol succeeds if and only if (i) all the exchange times are less than or equal to the maximum value  $\Delta t_{max}$  and (ii) all the responses are correct.

*Memory requirements.* The proposed protocol requires an amount of memory of  $(n - u + 2)2^u - 2$  bits. The length of the first  $u$  registers  $B^1, B^2, \dots, B^u$  is  $2^1, 2^2, \dots, 2^u$ , respectively. The remaining ones  $B^{u+1}, \dots, B^n$  have  $2^u$  bits each one. So, in total we have  $\sum_{i=1}^u 2^i + (n - u)2^u$  bits, which is  $(2^{u+1} - 2) + (n - u)2^u = (n - u + 2)2^u - 2$ .

## 7. Conclusions

We have developed an abstract model, based on finite state automata, for the description of a class of precomputation-based distance-bounding protocols. Execution of a protocol's slow phase is represented by randomly

selecting one instance from a set of automata, while the execution of the protocol's fast phase is represented by a walk through the selected automaton. Our model is sufficiently expressive to describe many published protocols, among which the well-known HK protocol and the Tree-based protocol.

The virtue of this model is that it supports generic analysis of members of this protocol class. For instance, we can analyze the security limits of a protocol in relation to the number of rounds. Further, we introduced the notion of uniformity, which expresses that randomly chosen walks through the automaton have no bias towards a particular state. Finally, we developed a family of uniform protocols in our model and proved that it has an excellent performance in relation to its memory requirements.

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